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LDROBOT

SHENZHEN LDROBOT CO., LTD

深圳樂動機器人股份有限公司

(A joint stock company incorporated in the People's Republic of China with limited liability)

(Stock Code: 1236)

VOLUNTARY ANNOUNCEMENT ENTERING INTO A STRATEGIC COOPERATION AGREEMENT IN THE PHYSICAL AI SECTOR

This announcement is made by SHENZHEN LDROBOT CO., LTD (the “**Company**”, together with its subsidiaries, the “**Group**”) on a voluntary basis.

The Board of Directors (the “**Board**”) of the Company is pleased to announce that the Company has recently formally entered into a strategic cooperation agreement (the “**Cooperation Agreement**”) with Minieye Technology Co., Ltd (“**Minieye**”). Both parties aim to fully leverage their respective technological strengths and market resources in the fields of robotics and autonomous driving, with a focus on the co-creation of physical AI technology, full-scenario implementation and industrial ecosystem empowerment. Leveraging the Group’s physical AI infrastructure capabilities anchored in “perception gateways + data foundations,” alongside its R&D capabilities for complete embodied robot products and global robotic ecosystem resources, and synergizing with Minieye’s end-to-end large-scale model technology powered by data flywheels and multi-modal intelligent interaction technologies, both parties will jointly develop cross-scenario physical AI solutions, collectively expand the boundaries of mobile robotics applications and strive to become a global benchmark in the physical AI industry.

COOPERATION AGREEMENT

Pursuant to the Cooperation Agreement, both parties will engage in in-depth collaboration in the fields of physical AI and embodied intelligence adhering to the principles of “complementary strengths and win-win cooperation”. The cooperation will primarily focus on the following areas:

1. **To jointly build a physical AI technology foundation.** Leveraging the Group’s full-stack capabilities in physical AI spatial perception algorithms and models, the development and application of embodied robots as well as real-world data and spatial assets, and drawing on Minieye’s deep expertise in end-to-end autonomous driving models, physical AI algorithms and closed-loop data systems from massive real-world scenarios, both parties will collaborate on the development of world models for general physical intelligence.
2. **To jointly build a full-scenario physical AI product matrix.** By integrating the Group’s strengths in physical AI spatial perception technology, data and embodied robotics productization with Minieye’s strengths in autonomous driving technology, data and engineering, both parties will jointly develop integrated hardware-software solutions for physical AI application scenarios, thereby addressing the challenges of last-mile delivery. Meanwhile, leveraging both parties’ accumulated expertise in interactive intelligence technologies in physical AI, both parties will jointly develop an end-to-end multi-modal interactive large model focused on “empathetic, real-time, and anthropomorphic” human-machine dialogue and action interaction, and jointly launch robotic products centered on delivering “emotional value” as a core output.
3. **To promote scenario implementations and commercialization synergy.** Both parties will co-create flagship demonstration projects, prioritizing cities where Minieye’s autonomous vehicles have been deployed, such as Shenzhen and Changsha, and selecting scenarios such as industrial parks, smart communities and logistics parks to build end-to-end unmanned demonstration bases featuring “robots and autonomous vehicles”. This initiative aims to validate the feasibility of physical AI solutions and crystallize a replicable implementation model. Concurrently, both parties will launch coordinated global brand initiatives and make ecosystem-building efforts, and jointly participate in industry events such as robotics summits and international auto shows, while collaborating with upstream and downstream enterprises in the industry chain (including sensor manufacturers, chipmakers and scenario operators) to build a physical AI industrial ecosystem and drive alignment on technical standards.

4. **Strengthen data and resource synergy to solidify the fundamentals of physical AI.** Both parties will engage in in-depth collaboration on the development of data infrastructure in the fields of physical AI and embodied intelligence, integrating the data collection pipelines between the Group's robotics platform and Minieye's vehicle platform to establish a unified, cross-platform data loop; jointly build a high-quality scenario library covering both indoor and outdoor, high-quality repository of structured and unstructured scenarios; collaborate to establish high-fidelity simulation and testing environments; jointly develop data standards and annotation guidelines; explore the establishment of a unified data governance framework; and create a virtuous cycle of continuous data-driven algorithm iteration, thereby providing robust data support for the research, development, and upgrading of foundational physical intelligence models.
5. Specific plans for joint product development and implementation shall be subject to the "joint development agreement" to be executed separately by both parties.

REASONS FOR AND BENEFITS OF SIGNING THE COOPERATION AGREEMENT

As the core technology connecting digital intelligence with the physical world, physical AI is driving the mobile robot and intelligent driving industries to transform from "isolated technology" to "full-scenario embodied intelligence", becoming the core growth engine of the trillion-level physical intelligence application market. Both parties have significant technological complementarity and strong scenario synergy in the fields of embodied robots and intelligent driving, possessing a solid foundation for cooperation and broad market potential.

This collaboration aligns with the development trends of physical AI and embodied intelligence industries, fully leveraging the Group's core capabilities in physical AI spatial perception, the R&D of complete embodied robots, and the development of a global channel ecosystem, as well as Minieye's advantages in L2+ to L4 autonomous driving, automotive-grade mass production experience, and multi-modal interaction large models.

The Board believes that this strategic cooperation will accelerate the transition of physical AI technology from R&D to large-scale implementation, expand the scope of applications for robots and autonomous vehicles, enhance the overall competitiveness of both parties' products and their global expansion capabilities, and contribute to the high-quality development of the industry.

ABOUT MINIEYE

Minieye is committed to shaping an automotive intelligence ecosystem through technological innovations to improve road safety and enhance driving experiences. We focus on the innovation and implementation of technologies in intelligent driving, intelligent cabin, smart mobility, and smart logistics. Leveraging our full-stack in-house platform technology, integrated hardware-software R&D capabilities and advanced mass production capability, and adhering to the strategy of “customer-first, scenario-focused, iterative product development, and boundary expansion”, we continue to develop solutions with improving automation level, striving to become a key driver of intelligent transformation in the industry. The H Shares of Minieye are listed on the Main Board of The Stock Exchange of Hong Kong Limited (Stock Code: 2431).

ABOUT THE GROUP’S BUSINESS

The Group is committed to empowering robots with perception to understand the physical world. As a globally leading full-stack robot company driven by perception intelligence, the Company has built comprehensive capabilities spanning from underlying technologies to advanced application implementations in the field of intelligent robotics, leveraging its multi-modal perception products, AI spatial intelligence models and algorithms, and a highly efficient universal robot development platform. Starting from the core of perception, LDROBOT identifies and addresses the diverse needs emerging within the evolving robotics industry. By actively expanding into the vertical robot market, the Company drives the application of embodied robots to improve everyone’s lives.

By order of the Board
SHENZHEN LDROBOT CO., LTD
ZHOU Wei
Chairman of the Board

Hong Kong, June 11, 2026

As of the date of this announcement, the Board comprises Mr. ZHOU Wei, Mr. GUO Gaihua and Mr. ZHANG Jun as executive directors, Dr. HUANG Xi as non-executive director, and Mr. CHENG Hao, Dr. YAN Hongyu and Mr. HONG Kam Le as independent non-executive directors.